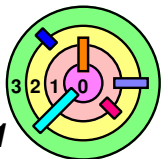


Handling Signals

- ➡ Two ways to handle signals
- ▬ handling it *asynchronously*
 - using *signal handlers*
 - ▬ handling it *synchronously*
 - using `sigwait()` in a signal-catching thread



Handling Signals Asynchronously



Signal handler

- each signal in a *process* can have *at most one handler*
- to specify a signal handler of a process, use:
 - `sigset/signal()`
 - ◆ returns the current handler (which could be the "default handler")
 - `sigaction()`
 - ◆ more functionality

```
#include <signal.h>
```

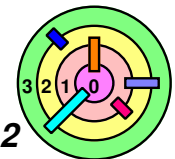
```
typedef void (*sighandler_t) (int);
```

```
sighandler_t sigset(int signo, sighandler_t handler);
```

```
sighandler_t signal(int signo, sighandler_t handler);
```

```
sighandler_t OldHandler = sigset(SIGINT, NewHandler);
```

- signal handler is part of the *context* of a process



Special Handlers



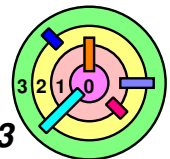
SIG_DFL

- use the default handler
- usually terminates the process
- `sigset/signal(SIGINT, SIG_DFL);`



SIG_IGN

- ignore the signal
- `sigset/signal(SIGINT, SIG_IGN);`



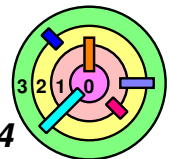
Example

```
#include <signal.h>
```

```
int main() {  
    void handler(int);  
  
    sigset(SIGINT, handler);  
    while(1)  
        ;  
    return 1;  
}
```

```
void handler(int signo) {  
    printf("I received signal %d. Whoopee!!\n", signo);  
}
```

- ⇒ *SIGINT is blocked* inside handler()
- ⇒ but how do you kill this program from your console?
 - can use the "kill" shell command, e.g., "kill -15 <pid>"
- ⇒ instead of using sigset(), you can also use sigaction()



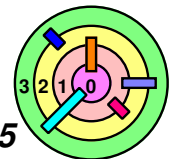
Example

```
#include <signal.h>
```

```
int main() {  
    void handler(int);  
  
    sigset(SIGINT, handler);  
    while(1)  
        ;  
    return 1;  
}
```

```
void handler(int signo) {  
    printf("I received signal %d. Whoopee!!\n", signo);  
    sigset(SIGINT, handler);  
}
```

← in some systems, you may have to re-establish the signal handler inside the signal handler if you want to receive the same signal more than once



sigaction

```
int sigaction(int sig,
              const struct sigaction *new,
              struct sigaction *old);

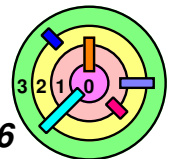
struct sigaction {
    void (*sa_handler)(int);
    void (*sa_sigaction)(int, siginfo_t *, void *);
    sigset_t sa_mask;
    int sa_flags;
};
```



sigaction() allows
for more complex
behavior

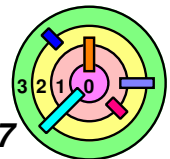
— e.g., block *additional*
signals (specified by
sa_mask) when
handler is called

```
int main() {
    struct sigaction act;
    void sighandler(int);
    sigemptyset(&act.sa_mask);
    act.sa_flags = 0;
    act.sa_handler = sighandler;
    sigaction(SIGINT, &act, NULL);
    ...
}
```



Async-Signal Safety

- ➡ The problem with *asynchronous signal* is that you have to worry about *async-signal safety*
 - if you don't take care of it just right, bad things can happen
- ➡ *Async-Signal Safety*: Make your code safe when working with *asynchronous signals*
- ➡ The general rule to provide async-signal safety:
 - any data structure the signal handler accesses must be async-signal safe
 - i.e., an async signal must not corrupt data structures
- ➡ An alternative is to make async-signal synchronous
 - use a *signal-catching thread* to receive a particular signal

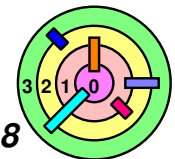


Example 1: Waiting for a Signal

```
sigset (SIGALRM, DoSomethingInteresting);  
...  
struct timeval waitperiod = {0, 1000};  
    /* seconds, microseconds */  
struct timeval interval = {0, 0};  
struct itimerval timerval;  
  
timerval.it_value = waitperiod;  
timerval.it_interval = interval;  
  
setitimer(ITIMER_REAL, &timerval, 0);  
    /* SIGALRM sent in ~one millisecond */  
  
pause(); /* wait for it */
```

— can SIGALRM occur before pause() is called?

➡ Note: strickly speaking, this is *not* a deadlock
— it has a *race condition*



Example 2: Status Update

```
#include <signal.h>

computation_state_t state;

int main() {
    void handler(int);
    sigset(SIGINT, handler);
    long_running_proc();
    return 0;
}

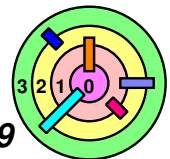
void long_running_proc() {
    while (a_long_time) {
        update_state(&state);
        compute_more();
    }
}

void handler(int signo) {
    display(&state);
}
```

- ⇒ long-running job that can take days to complete
 - the handler() can be used to print a progress report
 - need to make sure that state is in a consistent state
 - this is a synchronization issue
 - our handler() is not *async-signal safe*

➡ Note: this is *not* a deadlock and really not a race condition

- ⇒ this is the case where the code is not async signal safe



Example 2: Status Update

```
void long_running_proc() {  
    while (a_long_time) {  
        pthread_mutex_lock(&m);  
        update_state(&state);  
        pthread_mutex_unlock(&m);  
        compute_more();  
    }  
}
```

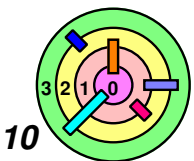
```
void handler(int signo) {  
    pthread_mutex_lock(&m);  
    display(&state);  
    pthread_mutex_unlock(&m);  
}
```



Does this work?

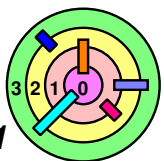
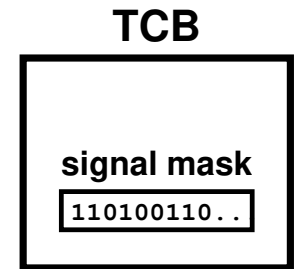
- no (*this code is **not reentrant***)
- it may get stuck in handler()
- signal handler gets executed till **completion**
 - in general, keep it simple and brief

— yes, you can deadlock with yourself even if you only have one thread



Masking (Blocking) Signals

- ➡ Solution: control signal delivery by *masking/blocking the signal*
- don't mask/block all signals, just the ones you want
 - a set of signals is represented as a set of bits called `sigset_t`
 - which is just an unsigned `int`
 - if a mask bit is 1, the corresponding signal is *blocked*; otherwise, the corresponding signal is *unblocked*
 - when a child thread is created, it *inherits* signal mask from the parent thread



Masking (Blocking) Signals

➡ To examine or change the signal mask of the calling process

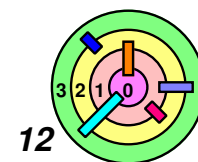
```
#include <signal.h>
int sigprocmask(
    int how,
    const sigset_t *set,
    sigset_t *old);
```

TCB

signal mask
110100110..

➡ how is one of three commands:

- SIG_BLOCK: the new signal mask is the union of the current signal mask and (*set)
- SIG_UNBLOCK: the new signal mask is the intersection of the current signal mask and the complement of (*set)
- SIG_SETMASK: the new signal mask is (*set)



sigset_t

- ➡ There are bunch of functions to manipulate `sigset_t`
- ➡ be careful, with *some APIs*, 1 means to *allowed/unblock* a signal, and with other APIs, 1 means to *blocked* a signal

TCB

signal mask
110100110...

- ➡ To clear a set:

```
int sigemptyset(sigset_t *set);
```

- ➡ To add or remove a signal from the set:

```
int sigaddset(sigset_t *set, int signo);
int sigdelset(sigset_t *set, int signo);
```

- ➡ Example: to refer to both SIGHUP and SIGINT:

```
sigset_t set;
```

```
sigset_t set;
```

```
sigemptyset(&set);
```

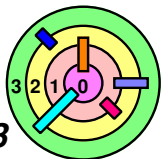
```
sigfillset(&set);
```

```
sigaddset(&set, SIGHUP);
```

```
sigdelset(&set, SIGHUP);
```

```
sigaddset(&set, SIGINT);
```

```
sigdelset(&set, SIGINT);
```



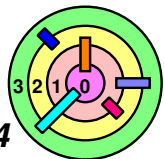
Example 1: Correct Way of Waiting for a Signal

```

sigset_t set, oldset;
sigemptyset(&set);
sigaddset(&set, SIGALRM);
sigprocmask(SIG_BLOCK, &set, &oldset);
    /* SIGALRM now masked */
setitimer(ITIMER_REAL, &timerval, 0);
    /* SIGALRM sent in ~one millisecond */
sigfillset(&set);
sigdelset(&set, SIGALRM);
sigsuspend(&set); /* wait for it safely */
    /* SIGALRM masked again */
...
sigprocmask(SIG_SETMASK, &oldset, (sigset_t *)0);
    /* SIGALRM unmasked */

```

- = sigsuspend() *replaces* the caller's signal mask with the set of signals pointed to by the argument
 - in the above, all signals are blocked/masked except for SIGALRM
 - *atomically unblocks* the signal and *waits* for the signal



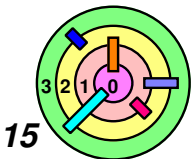
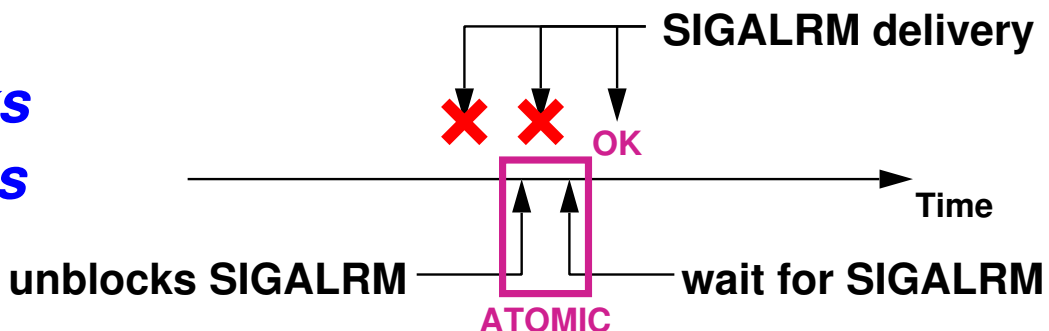
Example 1: Correct Way of Waiting for a Signal

```

sigset_t set, oldset;
sigemptyset(&set);
sigaddset(&set, SIGALRM);
sigprocmask(SIG_BLOCK, &set, &oldset);
    /* SIGALRM now masked */
setitimer(ITIMER_REAL, &timerval, 0);
    /* SIGALRM sent in ~one millisecond */
sigfillset(&set);
sigdelset(&set, SIGALRM);
sigsuspend(&set); /* wait for it safely */
    /* SIGALRM masked again */
...
sigprocmask(SIG_SETMASK, &oldset, (sigset_t *)0);
    /* SIGALRM unmasked */

```

- ▣ sigsuspend()
 - *atomically unblocks* the signal and *waits* for the signal



Async-Signal Safety

- ➡ There is only **one** correct way to wait for an asynchronous event **you generated**
- ➡ e.g., an alarm that **you** wind up and wait for is an asynchronous event you generate

Step 1) **block** the asynchronous event

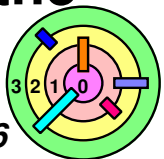
Step 2) do something that will cause the asynchronous event to get generated

Step 3) **unblock** the event and **wait** for the event in **one atomic operation**

- ➡ There is only **one** correct way to wait for an asynchronous event **someone else generated**
- ➡ e.g., wait for a guard to become true in a guarded command

Step 1) **block** the asynchronous event

Step 2) check if the event has been generated, if not, **unblock** the event and **wait** for the event in **one atomic operation**



Example 2: Correct Way to Handle Status Update

```
#include <signal.h>

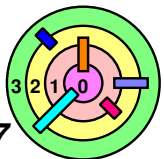
computation_state_t state;
sigset_t set;

int main() {
    void handler(int);
    sigemptyset(&set);
    sigaddset(&set, SIGINT);
    sigset(SIGINT, handler);
    long_running_proc();
    return 0;
}
```

— now SIGINT cannot be delivered in
update_state()

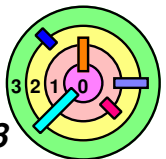
```
void long_running_proc() {
    while (a_long_time) {
        sigset_t old_set;
        sigprocmask(
            SIG_BLOCK,
            &set,
            &old_set);
        update_state(&state);
        sigprocmask(
            SIG_SETMASK,
            &old_set,
            0);
        compute_more();
    }
}

void handler(int signo) {
    display(&state);
}
```



Signals and Threads

- ➡ In Unix, signals are sent to *processes*, not threads!
 - in a single-threaded process, it's obvious which thread would handle the signal
 - in a multi-threaded process, it's not so clear
 - in POSIX, the signal is delivered to a thread chosen *at random*
- ➡ What about the signal mask (i.e., blocked/enabled signals)?
 - should one set of sigmask affect all threads in a process?
 - or should each thread gets it own sigmask?
 - this certainly makes more sense
- ➡ POSIX rules for a multithreaded process:
 - the thread that is to receive the signal is chosen *randomly* from the set of threads that do not have the signal blocked
 - if all threads have the signal blocked, then the signal remains pending until some thread unblocks it
 - ◇ at which point the signal is delivered to that thread
 - child thread *inherits* signal mask from parent thread



Synchronizing Asynchrony

```

some_state_t state;
sigset_t set;

main() {
    pthread_t thread;
    sigemptyset(&set);
    sigaddset(&set,
              SIGINT);
    sigprocmask(
        SIG_BLOCK,
        &set, 0);
    // main thread
    //      blocks SIGINT
    pthread_create(
        &thread, 0,
        monitor, 0);
    long_running_proc();
}

```

```

void long_running_proc() {
    while (a_long_time) {
        pthread_mutex_lock(&m);
        update_state(&state);
        pthread_mutex_unlock(&m);
        compute_more();
    }
}

void *monitor() {
    int sig;
    while (1) {
        sigwait(&set, &sig);
        pthread_mutex_lock(&m);
        display(&state);
        pthread_mutex_unlock(&m);
    }
    return(0);
}

```

— this is **PREFERRED**, no need for signal handler!

sigwait

```
int sigwait(sigset_t *set, int *sig)
```

- ➡ `sigwait()` blocks until a signal specified in `set` is received
 - return which signal caused it to return in `sig`
 - if you have a signal handler specified for `sig`, it will *not* get invoked when the signal is delivered
 - instead, `sigwait()` will return
- ➡ You should make sure that all the threads in your process have these signals blocked!
 - this way, when `sigwait()` is called, the calling thread temporarily becomes the *only* thread in the process who can receive the signal
- ➡ `sigwait(set)` *atomically unblocks* signals specified in `set` and *waits* for signal delivery

