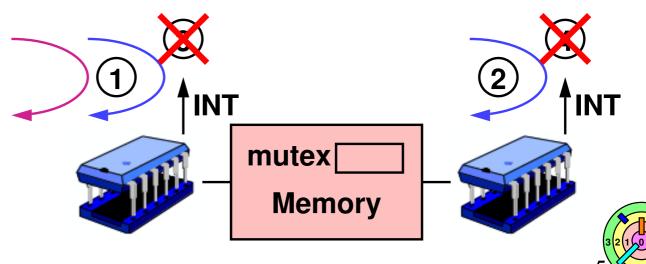
5.1 Threads Implementations

- Strategies
- A Simple Thread Implementation
- Multiple Processors



&NextThread->context);

Straight-threads - Multiple Processors



thread_switch() is no longer sufficient

it's meant for uniprocessor



Simple approach

run on each processor an idle thread

```
void idle_thread() {
  while(1) {
    enqueue(runqueue, CurrentThread)
    thread_switch()
  }
}
```

void thread_switch() {

thread_t NextThread, OldCurrent;
NextThread = dequeue(RunQueue);

swapcontext(&OldCurrent->context,

OldCurrent = CurrentThread;
CurrentThread = NextThread;

- this thread never blocks, so there is always something to run to avoid boundary condition (although this is busy-waiting)
- code is incomplete (because thread_switch() is incomplete, the way it was presented here)
- normal threads join the RunQueue when ready



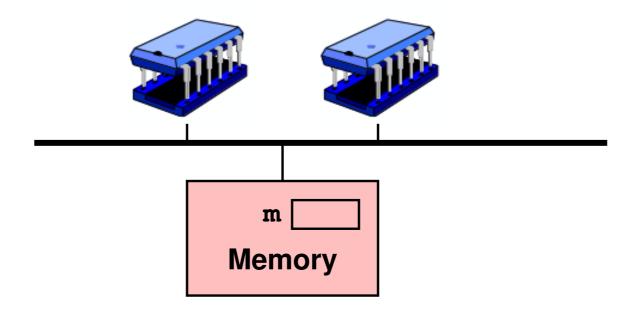
Straight-threads - Multiple Processors



When there are multiple processors, the difficulty lies in locking

```
if (!m->locked) {
  m->locked = 1;
}
```

if both threads execute the above code concurrently, in different processors, both threads think they got the lock





No way to implement this with only software





```
int CAS(int *ptr, int old, int new) {
   int tmp = *ptr; // get the value of mutex
   if (tmp == old) // if it equals to old
      *ptr = new; // set it to new
   return tmp; // return old
}
```

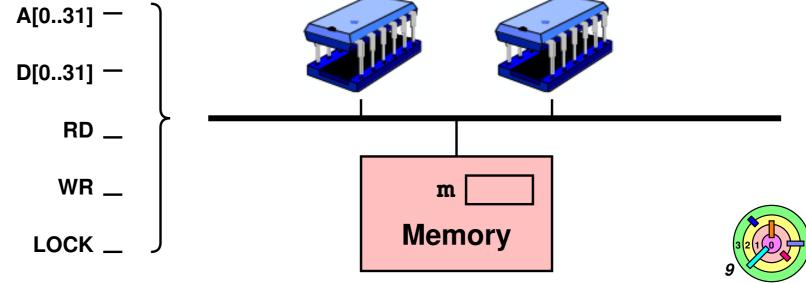
- often implemented as a machine-level instruction
 - must execute atomically
 - how do you guarantee that when there are multiple CPUs?





```
int CAS(int *ptr, int old, int new) {
   int tmp = *ptr; // get the value of mutex
   if (tmp == old) // if it equals to old
       *ptr = new; // set it to new
   return tmp; // return old
}
```

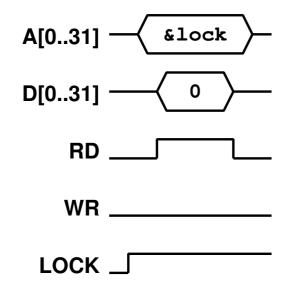
- e.g., assume mutex is unlocked, call CAS (&lock, 0, 1)
 - mutex is represented as a bit, 0 if unlocked, 1 if locked

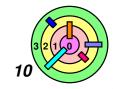




```
int CAS(int *ptr, int old, int new) {
  int tmp = *ptr; // get the value of mutex
  if (tmp == old) // if it equals to old
     *ptr = new; // set it to new
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}
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- e.g., assume mutex is *unlocked*, call CAS (&lock, 0, 1)
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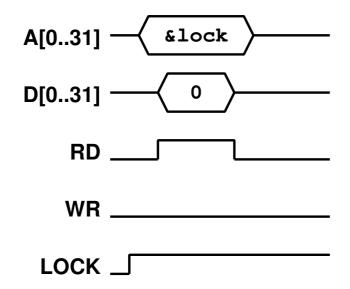


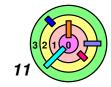




```
int CAS(int *ptr, int old, int new) {
   int tmp = *ptr; // get the value of mutex
   if (tmp == old) // if it equals to old
        *ptr = new; // set it to new
   return tmp; // return old
}
```

- e.g., assume mutex is *unlocked*, call CAS (&lock, 0, 1)
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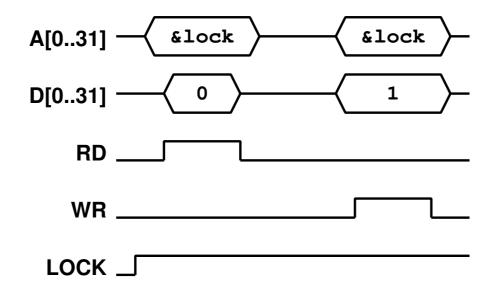


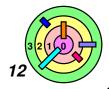




```
int CAS(int *ptr, int old, int new) {
   int tmp = *ptr; // get the value of mutex
   if (tmp == old) // if it equals to old
        *ptr = new; // set it to new
        return tmp; // return old
}
```

- e.g., assume mutex is *unlocked*, call CAS (&lock, 0, 1)
 - mutex is represented as a bit, 0 if unlocked, 1 if locked

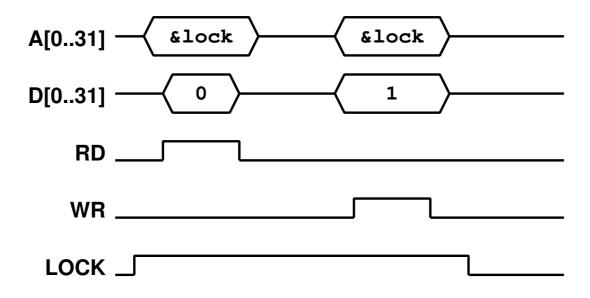


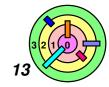




```
int CAS(int *ptr, int old, int new) {
   int tmp = *ptr; // get the value of mutex
   if (tmp == old) // if it equals to old
        *ptr = new; // set it to new
   return tmp; // return old
}
```

- e.g., assume mutex is *unlocked*, call CAS (&lock, 0, 1)
 - mutex is represented as a bit, 0 if unlocked, 1 if locked

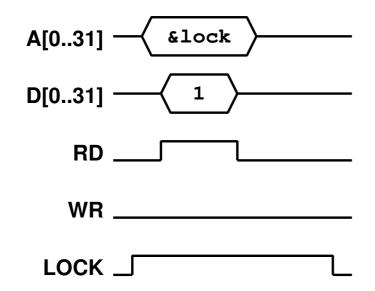


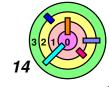




```
int CAS(int *ptr, int old, int new) {
   int tmp = *ptr; // get the value of mutex
   if (tmp == old) // if it equals to old
      *ptr = new; // set it to new
   return tmp; // return old
}
```

- e.g., assume mutex is locked, call CAS (&lock, 0, 1)
 - mutex is represented as a bit, 0 if unlocked, 1 if locked



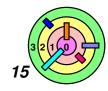


```
int CAS(int *ptr, int old, int new) {
   int tmp = *ptr; // get the value of mutex
   if (tmp == old) // if it equals to old
      *ptr = new; // set it to new
   return tmp; // return old
}
```

- Can implement spin lock using CAS ()
 - mutex is represented as a bit, 0 if unlocked, 1 if locked
- Naive spin lock

```
void spin_lock(int *mutex) {
    while(CAS(mutex, 0, 1)) // textbook is wrong
    ;
}

void spin_unlock(int *mutex) {
    *mutex = 0;
}
```



Spin Lock

```
Naive spin lock
```

```
void spin_lock(int *mutex) {
    while(CAS(mutex, 0, 1)) // textbook is wrong
    ;
}

void spin_unlock(int *mutex) {
    *mutex = 0;
}
```

Better spin lock

```
void spin_lock(int *mutex) {
  while (1) {
    if (*mutex == 0) {
        // the mutex was at least momentarily unlocked
        if (!CAS(mutex, 0, 1))
            break; // we have locked the mutex
        // some other thread beat us to it, try again
    }
}
```

Blocking Locks



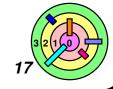
Spin locks are wasteful

- processor time wasted waiting for the lock to be released
- barely acceptable if locks are held only briefly



A better approach is to have a blocking lock

- threads wait by having their execution suspended
- a thread much yield the processor and join a queue of waiting threads
 - later on, get resumed explicitly

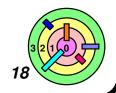


Blocking Locks

```
void blocking_lock(mutex_t *m) {
  if (m->holder != 0) {
    enqueue (m->wait_queue, CurrentThread);
    thread_switch();
  } else
    m->holder = CurrentThread;
void blocking_unlock(mutex_t *m) {
  if (queue_empty(m->wait_queue))
    m->holder = 0;
  else {
    m->holder = dequeue(m->wait_queue);
    enqueue (RunQueue, m->holder);
```



This code only works on a uniprocessor



Blocking Lock Failure Scenario (1)

```
void blocking_lock(mutex_t *m) {
  if (m->holder != 0)
    enqueue (m->wait_queue, CurrentThread);
    thread_switch();
   else
    m->holder = CurrentThread;
void blocking_unlock(mutex_t *m) {
  if (queue_empty(m->wait_queue))
    m->holder = 0;
  else {
    m->holder = dequeue(m->wait_queue);
    enqueue (RunQueue, m->holder);
```



On a multiprocessor, it may not work (since it has a race condition)

threads 1 and 2 can both think they've got the lock



Blocking Lock Failure Scenario (2)

```
void blocking_lock(mutex_t *m) {
  if (m->holder != 0) {
    enqueue (m->wait_queue, CurrentThread);
    thread_switch();
    else
    m->holder = CurrentThread;
void blocking_unlock(mutex_t *m) {
  if (queue_empty(m->wait_queue))
    m->holder = 0;
  else {
    m->holder = dequeue(m->wait_queue);
    enqueue (RunQueue, m->holder);
```



- thread 2 holds the mutex and wait queue is empty and thread 1 tries to lock the mutex at the same time thread 2 is releasing the mutex
- thread 1 may wait forever

Blocking Lock Failure Scenario (2)

```
void blocking_lock(mutex_t *m) {
  if (m->holder != 0) {
    enqueue (m->wait_queue, CurrentThread);
    thread_switch();
    else
    m->holder = CurrentThread;
void blocking_unlock(mutex_t *m) {
  if (queue_empty(m->wait_queue))
    m->holder = 0;
  else {
    m->holder = dequeue(m->wait_queue);
    enqueue (RunQueue, m->holder);
```

Maybe we can fix both scenarios by making these two functions mutually exclusive (with respect to mutex m)

maybe we can using a spin lock!

```
void blocking_lock(mutex_t *m) {
  spin_lock(m->spinlock); // okay to spin here
  if (m->holder != 0) {
    enqueue (m->wait_queue, CurrentThread);
    thread switch();
  } else {
    m->holder = CurrentThread;
  spin_unlock (m->spinlock);
void blocking_unlock(mutex_t *m) {
  spin_lock(m->spinlock); // okay to spin here
  if (queue_empty(m->wait_queue)) {
    m->holder = 0;
  } else {
    m->holder = dequeue(m->wait_queue);
    enqueue (RunQueue, m->holder);
  spin_unlock (m->spinlock);
```



Will deadlock because of thread_switch()



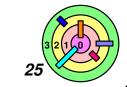
```
void blocking_lock(mutex_t *m) {
  spin_lock (m->spinlock);
  if (m->holder != 0) {
    enqueue (m->wait_queue, CurrentThread);
    spin_unlock(m->spinlock);
    thread_switch();
  } else {
    m->holder = CurrentThread;
    spin_unlock (m->spinlock);
void blocking_unlock(mutex_t *m) {
  spin_lock (m->spinlock);
  if (queue_empty(m->wait_queue)) {
    m->holder = 0;
  } else {
    m->holder = dequeue(m->wait_queue);
    enqueue (RunQueue, m->holder);
  spin_unlock(m->spinlock);
Has a different problem (race condition!)
```



```
void blocking_lock(mutex_t *m) {
  spin_lock (m->spinlock);
  if (m->holder != 0) {
    enqueue (m->wait_queue, CurrentThread);
    spin_unlock(m->spinlock);
    thread_switch();
  } else {
    m->holder = CurrentThread;
    spin_unlock (m->spinlock);
void blocking_unlock(mutex_t *m) {
  spin_lock (m->spinlock);
  if (queue_empty(m->wait_queue)) {
    m->holder = 0;
  } else {
    m->holder = dequeue(m->wait_queue);
    enqueue (RunQueue, m->holder);
  spin_unlock(m->spinlock);
Thread 1 may be running in both processors!
```



```
void blocking_lock(mutex_t *m) {
  spin_lock (m->spinlock);
  if (m->holder != 0) {
    enqueue (m->wait_queue, CurrentThread);
    spin_unlock(m->spinlock);
    thread_switch();
  } else {
    m->holder = CurrentThread;
    spin_unlock (m->spinlock);
void blocking_unlock(mutex_t *m) {
  spin_lock (m->spinlock);
  if (queue_empty(m->wait_queue)) {
    m->holder = 0;
  else {
    m->holder = dequeue(m->wait_queue);
    enqueue (RunQueue, m->holder);
  spin_unlock(m->spinlock);
Can you do spin_unlock() inside thread_switch()?
```



Futexes



Futex: Linux's fast user-space mutex (for 1×1 model)

- safe, efficient kernel conditional queueing in Linux
 - most of the time when you try to lock a mutex, it's unlocked; so just go ahead and lock it (no system call)
 - if it's locked (by another thread), then a system call is required for this thread to obtain the lock
- contained in it is an unsigned integer state called value and a queue of waiting threads



Two system calls are provided to support futexes

```
futex_wait(futex_t *futex, int val) {
  if (futex->val == val)
    // sleep on the futex queue inside kernel
}

futex_wake(futex_t *futex) {
    // wake up one thread from wait queue if
    // there is any
    ...
}
```

Ancillary Functions



Add 1 to *val, return its original value

```
unsigned int atomic_inc(unsigned int *val) {
   // performed atomically
   return((*val)++); // textbook is wrong
}
```

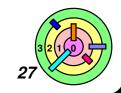
 e.g., x86 has "lock-prefixed instructions" so you can lock any consecutive machine instructions together and make them atomic

Subtract 1 to *val, return its original value

```
unsigned int atomic_dec(unsigned int *val) {
   // performed atomically
   return((*val)--); // textbook is wrong
}
```



Just like CAS(), both functions return the previous lock value



Attempt 1

```
f
```

```
futex->val
```

o means unlocked; otherwise, locked

```
void lock(futex_t *futex) {
  unsigned int c;
  while ((c = atomic_inc(&futex->val)) != 0)
    futex_wait(futex, c+1);
}

void unlock(futex_t *futex) {
  futex->val = 0;
  futex_wake(futex);
}
```



Problem with unlock()

slow because futex_wake() is a system call



Problem with lock()

- threads run in lock steps in a multiprocessor environment!
- futex->val may wrap-around



Attempt 2

- futex->val can only take on values of 0, 1, and 2
- 0 means unlocked
- 1 means locked but no waiting thread
- 2 means locked with the possibility of waiting threads

```
void lock(futex_t *futex) {
 unsigned int c;
  if ((c = CAS(\&futex->val, 0, 1) != 0)
    do {
      if (c == 2 | (CAS(&futex->val, 1, 2) != 0))
        futex_wait(futex, 2);
    } while ((c = CAS(&futex->val, 0, 2)) != 0));
void unlock(futex_t *futex) {
  if (atomic_dec(&futex->val) != 1) {
    futex->val = 0;
    futex_wake(futex);
```

textbook

is wrong

Attempt 2



Complications

```
void lock(futex_t *futex) {
                                                      textbook
  unsigned int c;
                                                      is wrong
  if ((c = CAS(\&futex->val, 0, 1) != 0)
    do {
      if (c == 2 | (CAS(&futex->val, 1, 2) != 0))
        futex wait(futex, 2);
    } while ((c = CAS(&futex->val, 0, 2)) != 0));
void unlock(futex_t *futex) {
  if (atomic_dec(&futex->val) != 1) {
    futex->val = 0;
    futex_wake(futex);
```

- the implementation of futex_wait() and futex_wake() must be atomic to avoid race conditions
 - https://www.akkadia.org/drepper/futex.pdf

Thread Synchronization Summary



- used if the duration of waiting is expected to be small
 - as in the case at the beginning of blocking_lock()
- Sleep (or blocking) locks
 - used if the duration of waiting is expected to be long
- Futexes
 - optimized version of blocking locks
- In your kernel assignmen #1, you need to implement *kernel* threads
 - very different from user threads
 - keep in mind that the weenix kernel is non-preemptive
 - the kernel is very powerful (and therefore, must be bug free, and therefore, your code must be bug free)
 - in kernel assignmen #3, you need to implement user threads/processes (well, MTP=0, still one thread per process)