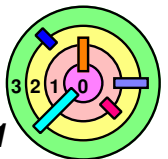


Warmup #2 (Part 2)

Bill Cheng

<http://merlot.usc.edu/william/usc/>

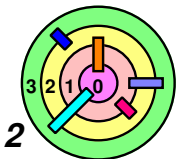
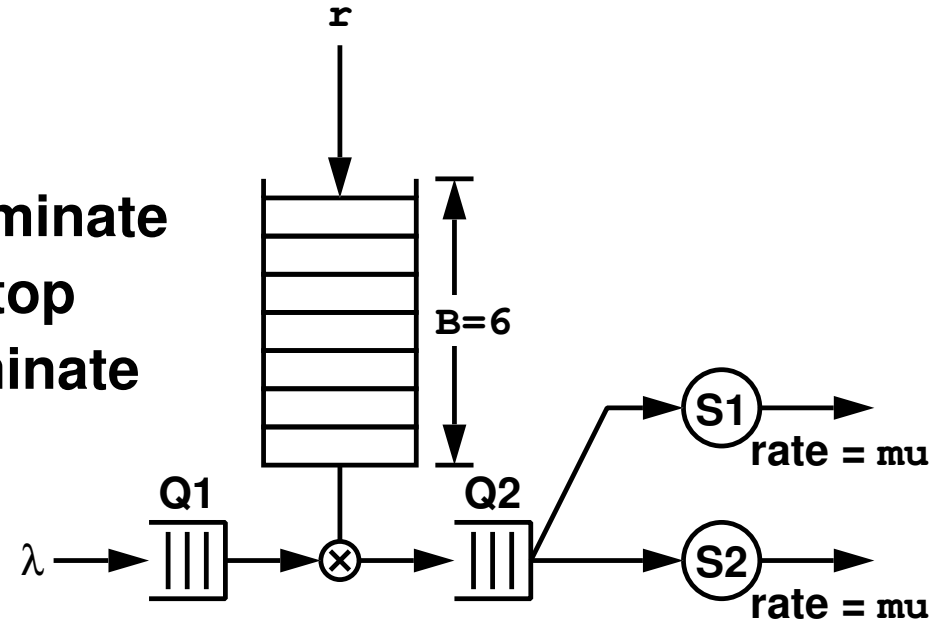


Handling <Ctrl+C> In Warmup #2



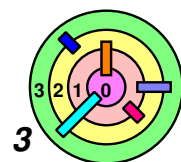
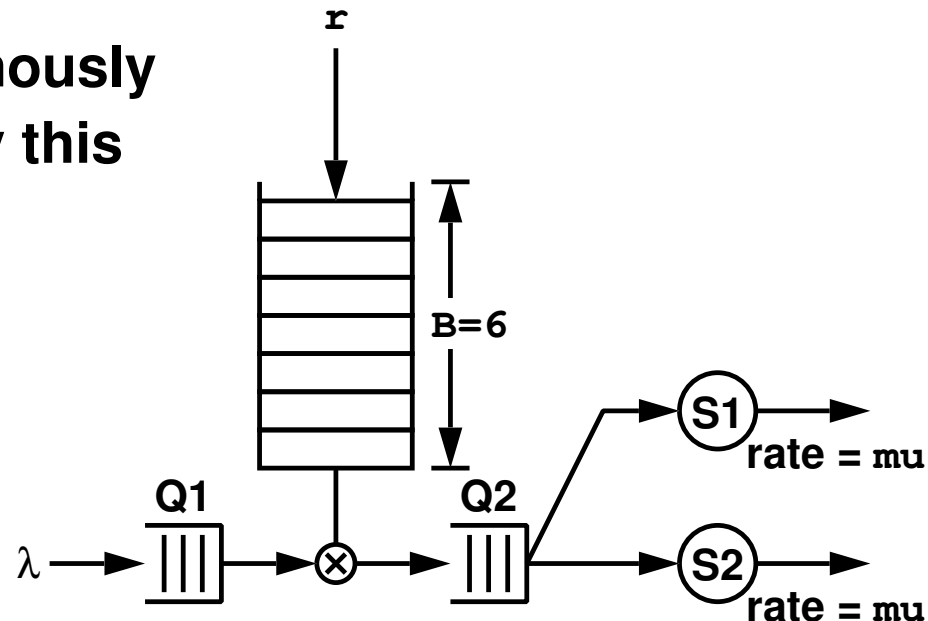
<Ctrl+C>

- packet arrival thread must stop generating packets and self-terminate
- token depositing thread must stop generating tokens and self-terminate
- a server thread must finish serving its current packet then self-terminate
- no packets or tokens must arrive
- need to take care of left-over packets that are stuck in Q1 and Q2
 - these are called "*removed packets*" because your simulator must remove them before you end your simulation
 - must distinguish 3 types of packets:
 - 1) *completed* packets
 - 2) *dropped* packets (packets that need $> B$ tokens)
 - 3) *removed* packets



Handling <Ctrl+C> In Warmup #2

- ➡ You can catch <Ctrl+C> asynchronously
- ▬ see lecture and understand why this is not a good idea
 - ▬ our recommendation is to *handle signals synchronously*
 - use a *signal-catching thread* and `sigwait()`
 - ◆ no signal handler at all
 - ▬ when <Ctrl+C> is caught, you should use the *pthread cancellation* mechanism to cancel packet and token threads
 - understanding thread cancellation will hopefully prevent you from make some mistakes in kernel assignment #1
 - ◆ although kernel cancellation is somewhat different from pthread cancellation



Designate A Thread To Catch A Signal

- ➡ Look at the man pages of `pthread_sigmask()` on Ubuntu 16.04
- designate child thread to handler SIGINT
 - parent thread blocks SIGINT (some code deleted and use SIGINT instead of SIGQUIT):

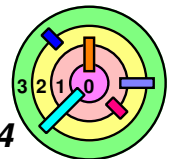
```
#include <pthread.h>

int
main(int argc, char *argv[])
{
    pthread_t thread;
    sigset_t set;
    int s;

    sigemptyset(&set);
    sigaddset(&set, SIGINT);
    sigaddset(&set, SIGUSR1);
    s = pthread_sigmask(SIG_BLOCK, &set, NULL);
    if (s != 0)
        handle_error_en(s, "pthread_sigmask");

    s = pthread_create(&thread, NULL, &sig_thread, (void *) &set);
    if (s != 0)
        handle_error_en(s, "pthread_create");

    pause();
}
```



pthread_sigmask()



Child thread example

- child thread unblocks SIGINT

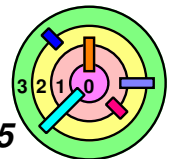
```
static void *  
sig_thread(void *arg)  
{  
    sigset_t *set = arg;  
    int s, sig;  
  
    for (;;) {  
        s = sigwait(set, &sig);  
        if (s != 0)  
            handle_error_en(s, "sigwait");  
        printf("Signal handling thread got signal %d\n", sig);  
    }  
}
```

- child thread is designated to handle SIGINT and SIGUSR1, no other thread will get SIGINT and SIGUSR1



Compile this code and run it

- press <Ctrl+C> to see that this program cannot be killed with <Ctrl+C>
- use "kill -15" command to kill this program



Example In Lecture

```

some_state_t state;
sigset_t set;

main() {
    pthread_t thread;
    sigemptyset(&set);
    sigaddset(&set,
              SIGINT);
    sigprocmask(
        SIG_BLOCK,
        &set, 0);
    // main thread
    //      blocks SIGINT
    pthread_create(
        &thread, 0,
        monitor, 0);
    long_running_proc();
}

```

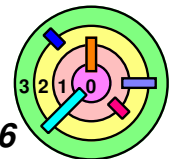
```

void long_running_proc() {
    while (a_long_time) {
        pthread_mutex_lock(&m);
        update_state(&state);
        pthread_mutex_unlock(&m);
        compute_more();
    }
}

void *monitor() {
    int sig;
    while (1) {
        sigwait(&set, &sig);
        pthread_mutex_lock(&m);
        display(&state);
        pthread_mutex_unlock(&m);
    }
    return(0);
}

```

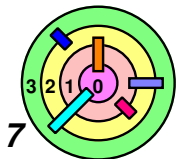
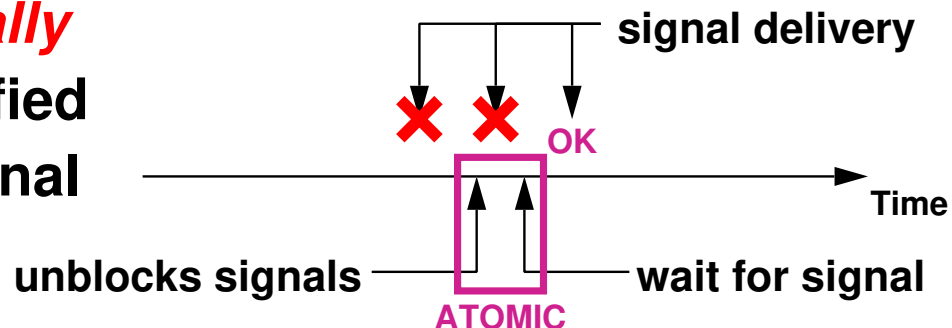
= this is the **PREFERRED** way to catch SIGINT for warmup2



sigwait ()

```
int sigwait(sigset_t *set, int *sig)
```

- ➡ `sigwait ()` blocks until a signal specified in `set` is received
 - return which signal caused it to return in `sig`
 - if you have a signal handler specified for `sig`, it will *not* get invoked when the signal is delivered
 - instead, `sigwait ()` will return
- ➡ You should make sure that all the threads in your process have these signals blocked!
 - this way, when `sigwait ()` is called, the calling thread temporarily becomes the *only* thread in the process who can receive the signal
- ➡ `sigwait (set)` *atomically unblocks* signals specified in `set` and *waits* for signal delivery



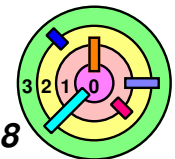
Warmup2 Catching <Ctrl+C> Made Easy

- ➡ Use a *<Ctrl+C>-catching thread* and *block SIGINT everywhere else*
- when `sigwait()` returns because <Ctrl+C> has been pressed:

```
lock mutex
set global flag /* time to quit gracefully */
cancel packet and token threads
broadcast CV
unlock mutex
self terminate
```

- according to spec, you must not cancel server threads

- ➡ Remember, if you don't use a <Ctrl+C>-catching thread, your regular threads can be borrowed to deliver signals
- your code must deal with that and that can get very messy

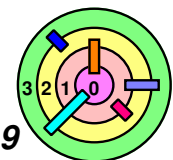


Warmup2 Cancellation Made Easy

- ➡ Only packet arrival and token depositing threads are allowed to be canceled
- use a <Ctrl+C>-catching thread (i.e., use `sigwait()`)
 - handling clean up with `pthread_cleanup_push()` and `pthread_cleanup_pop()` can be messy
 - it's good to use them in general, but for warmup2, maybe we should try to make our lives easier by observing this:
 - first procedure of packet or token thread looks like:

```
do-forever
    sleep();
    lock mutex
    /* stuff */
    unlock mutex
end-do
```

- if we have only one cancellation point, we know exactly where our threads will act on cancel

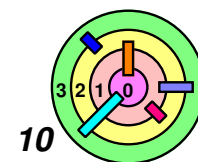


Warmup2 Cancellation Made Easy

- what if we change it to:

```
disable cancellation
do-forever
  enable cancellation
  sleep();
  disable cancellation
  lock mutex
  /* stuff */
  unlock mutex
end-do
```

- where can this thread act on cancel?
- would this make our thread "*unresponsive*" when <Ctrl+C> is pressed?
- there is a race condition in this code
 - ◆ what if the SIGINT-catching thread cancels this thread right when this thread is waiting for mutex lock?
 - ◆ must not create a new packet/token once you have printed the "SIGINT caught" message



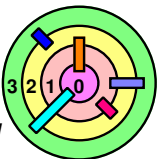
Statistics - Running Average

- ➡ Do not store all transmitted packets in a list and calculate statistics at the end of your simulation
 - it's a waste of memory
 - useful to learn how to write code with *small memory footprint*
 - keep a *running average* instead
 - just need one `int` and one `double`
 - ◆ `n` is the number of samples
 - ◆ `avg` is the average
 - ◆ when you get a new sample value, simply do:

```
avg = (n * avg + sample_value) / (n + 1)
n = n + 1
```

- avg above is $E[X]$, how do you calculate $E[X^2]$?

```
avg2 = (n * avg2 + sample_value^2) / (n + 1)
n = n + 1
```



Statistics - Running Average

— can you use running averages for all these statistics?

average packet inter-arrival time = <real-value>

average packet service time = <real-value>

average number of packets in Q1 = <real-value>

average number of packets in Q2 = <real-value>

average number of packets at S1 = <real-value>

average number of packets at S2 = <real-value>

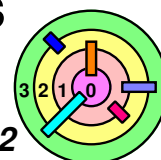
average time a packet spent in system = <real-value>

standard deviation for time spent in system = <real-value>

token drop probability = <real-value>

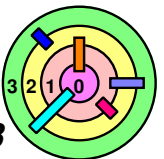
packet drop probability = <real-value>

- what should correspond to a sample value?
- what types of packet must you consider?
 - ◆ avg packet inter-arrival time must consider **all** packets
 - ◆ other averages must only consider **completed** packets
 - ◆ packet drop probability is # dropped / # arrived



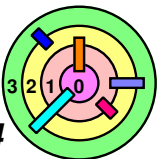
`gdb`

- ➡ When you get a breakpoint in `gdb`, what happened with other threads?
- ➡ If you break inside a signal handler and you type "`where`", how come `gdb` seems confused?



How To Learn New Concepts

- ➡ If there is a new concept that you are not familiar with, don't just try to write the final program
 - ▬ you won't know where the bugs are because you may not be clear about the concepts at multiple places
- ➡ Try writing small programs to test out ideas
 - ▬ try one idea at a time
 - ▬ use the debugger to get a better understanding of what's going on
 - ▬ then compile multiple ideas into one program and see if it works
- ➡ Ex:
 - ▬ `fork-wait.c`
 - ▬ `cat.c`
 - ▬ `redirect.c`
 - ▬ `thr-term.c`
 - ▬ `busywait.c`, `join.c`
 - ▬ `deadlock.c`, `trylock.c`
 - ▬ `whoopee.c`
 - ▬ `status-update.c`
 - ▬ `sigblock.c`, `sigwait.c`
 - ▬ `direct.c`
 - ▬ `cancel.c`
 - ▬ `three-threads.c`



defs.h

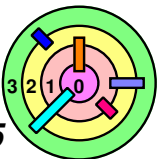
```
#ifndef _DEFS_H_
#define _DEFS_H_

#include <sys/types.h>
#include <sys/wait.h>
#include <unistd.h>
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <fcntl.h>
#include <signal.h>
#include <errno.h>

#include <pthread.h>

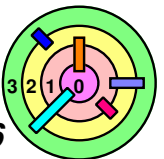
#ifndef NULL
#define NULL 0L
#endif /* ~NULL */

#endif /* _DEFS_H_ */
```



fork-wait.c

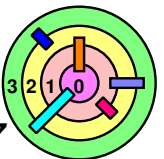
```
#include "defs.h"
#define NUM_CHILD 5
int sleep_time[NUM_CHILD], chd_num=0;
int main(int argc, char *argv[])
{
    srand48(time(0));
    for (chd_num=0; chd_num < NUM_CHILD; chd_num++) {
        sleep_time[chd_num] = lrand48() % 5000000;
        if (fork() == 0) {
            int pid=((int)getpid());
            printf("(Child) pid = %1d (0x%08x)\n", pid, pid);
            usleep(sleep_time[chd_num]);
            exit(child_pid+1);
        }
    }
    for (;;) {
        int pid=0, rc=0;
        if ((pid=wait(&rc)) == (-1)) break;
        printf("child %1d exited: 0x%08x.\n", pid, rc);
    }
    return 0;
}
```



cat.c

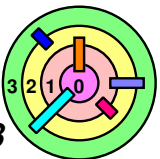
```
#include "defs.h"
#define BUFSIZE 1024
int main(int argc, char *argv[])
{
    char buf[BUFSIZE];
    int n=0;
    const char *note="Write failed\n";

    while ((n = read(0, buf, sizeof(buf))) > 0)
        if (write(1, buf, n) != n) {
            (void)write(2, note, strlen(note));
            exit(1);
        }
    return 0;
}
```



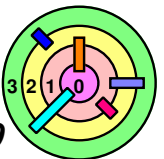
redirect.c

```
#include "defs.h"
int main(int argc, char *argv[])
{
    pid_t pid=(pid_t)0;
    if ((pid=fork()) == 0) {
        close(1);
        if (open("/tmp/Output",
                O_CREAT|O_WRONLY,
                0666) == -1) {
            perror("/tmp/Output");
            exit(1);
        }
        execl("/bin/date", "date", (char*)0);
        exit(1);
    }
    while(pid != wait(0)) ;
    return 0;
}
```



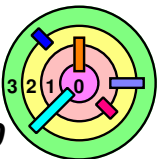
thr-term.c

```
#include "defs.h"
void *child(void *arg)
{
    if (*(int*)arg > 2) pthread_exit((void*)1);
    return((void*)2);
}
int main(int argc, char *argv[])
{
    pthread_t thread;
    void *result=NULL;
    pthread_create(&thread, 0, child, &argc);
    pthread_join(thread, (void**)&result);
    switch ((int)(long)result) {
    case 1: printf("result is 1\n"); break;
    case 2: printf("result is 2\n"); break;
    }
    return 0;
}
```



busywait.c

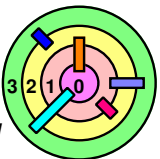
```
#include "defs.h"
#define NUM_THRS 100
int done[NUM_THRS];
pthread_t tid[NUM_THRS];
void *child(void *arg)
{
    int index=(int)(long)(arg);
    usleep(lrand48()%10000000);
    done[index] = 1;
    return 0;
}
int main(int argc, char *argv[])
{
    int i=0;
    memset(done, 0, sizeof(done));
    srand48(0);
    for (i=0; i < NUM_THRS; i++)
        pthread_create(&tid[i], 0, child, (void*)(long)i);
    waitall();
    return 0;
}
```



busywait.c

```
void waitall()
{
    for (;;) {
        int i=0, num_done=0;
        for (i=0; i < NUM_THRS; i++) {
            if (!done[i]) break;
            num_done++;
        }
        if (num_done == NUM_THRS) break;
    }
}
```

- ➡ Why is this busy wait?
 - the main thread is not doing anything useful
- ➡ Fix?
 - sleep for 100ms before checking
 - to avoid doing busy wait
 - not really a good solution



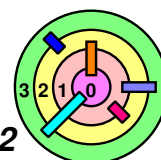
join.c



Real fix

— join with all threads

```
void waitall()  
{  
    int i=0;  
    for (i=0; i < NUM_THRS; i++)  
        pthread_join(tid[i], 0);  
}
```

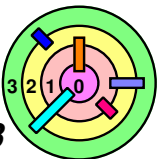


deadlock.c

➡ Try to deadlock child thread and main thread

```
#include "defs.h"
void *child(void *arg)
{
    for (;;) { proc1(); }
    return (void*) 0;
}

int main(int argc, char *argv[])
{
    pthread_t thread;
    srand48(time(0));
    pthread_create(&thread, 0, child, 0);
    for (;;) { proc2(); }
    return 0;
}
```



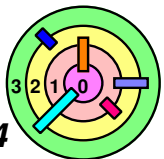
deadlock.c

```
pthread_mutex_t m1=PTHREAD_MUTEX_INITIALIZER;
pthread_mutex_t m2=PTHREAD_MUTEX_INITIALIZER;
```

```
void proc1() {
    pthread_mutex_lock(&m1);
    pthread_mutex_lock(&m2);
    printf("1");
    fflush(stdout);
    pthread_mutex_unlock(&m2);
    pthread_mutex_unlock(&m1);
    usleep(100000);
}
```

```
void proc2() {
    pthread_mutex_lock(&m2);
    pthread_mutex_lock(&m1);
    printf("2");
    fflush(stdout);
    pthread_mutex_unlock(&m1);
    pthread_mutex_unlock(&m2);
    usleep(100000);
}
```

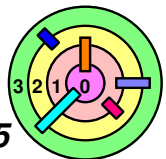
- ➡ Why no deadlock?
 - threads are alternating
- ➡ How to make it deadlock?
 - call `printf("-")` after locking `m1` in `proc1()` and call `printf("+")` after locking `m2` in `proc2()`
 - deadlock right away! (why?)



trylock.c

➡ How to use `trylock()` to avoid deadlock

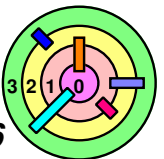
```
void proc2() {  
    while (1) {  
        pthread_mutex_lock(&m2);  
        printf("+");  
        fflush(stdout);  
        if (!pthread_mutex_trylock(&m1))  
            break;  
        pthread_mutex_unlock(&m2);  
    }  
    printf("2");  
    fflush(stdout);  
    pthread_mutex_unlock(&m1);  
    pthread_mutex_unlock(&m2);  
    usleep(100000);  
}
```



whoopee.c

➡ Let's catch SIGINT

```
#include "defs.h"
void handler(int signo)
{
    printf("Got signal %1d.  Whoopee!!\n", signo);
}
int main(int argc, char *argv[])
{
    sigset(SIGINT, handler);
    for (;;) { }
    return 1;
}
```



status-update.c

```

#include "defs.h"
typedef struct foo {
    int x, y;
} my_state;
my_state state;
int main() {
    state.x = state.y = 0;
    sigset(SIGINT, handler);
    long_running_proc();
    return 0;
}

void long_running_proc() {
    int i=0;
    for (i=0; i < 100; i++) {
        update_state(&state);
        compute_more();
    }
}

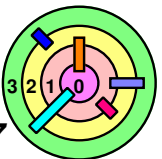
void handler(int signo) {
    display(&state);
}

void update_state(
    my_state *ptr) {
    ptr->x++;
    usleep(100000);
    ptr->y++;
}

void display(my_state *ptr) {
    printf("x = %1d\n", ptr->x);
    usleep(1000);
    printf("y = %1d\n", ptr->y);
}

void compute_more() { usleep(100000); }

```



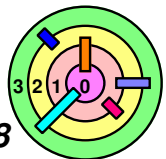
sigblock.c

➡ Let's block SIGINT

```
#include "defs.h"
typedef struct foo {
    int x, y;
} my_state;
my_state state;
sigset_t set;
int main() {
    state.x = state.y = 0;
    sigemptyset(&set);
    sigaddset(&set, SIGINT);
    sigset(SIGINT, handler);
    long_running_proc();
    return 0;
}
```

```
void long_running_proc() {
    int i=0;
    for (i=0; i < 100; i++) {
        sigset_t old_set;
        sigprocmask(SIG_BLOCK,
            &set, &old_set);
        update_state(&state);
        sigprocmask(SIG_SETMASK,
            &old_set, 0);
        compute_more();
    }
}

void handler(int signo) {
    display(&state);
}
```



sigwait.c

```

#include "defs.h"
typedef struct foo {
    int x, y;
} my_state;
my_state state;
sigset_t set;
pthread_mutex_t m=
PTHREAD_MUTEX_INITIALIZER;
int main() {
    pthread_t thr;
    state.x = state.y = 0;
    sigemptyset(&set);
    sigaddset(&set, SIGINT);
    sigprocmask(SIG_BLOCK,
        &set, 0);
    pthread_create(&thr, 0,
        monitor, 0);
    long_running_proc();
    return 0;
}

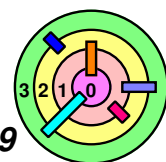
```

```

void long_running_proc() {
    int i=0;
    for (i=0; i < 100; i++) {
        pthread_mutex_lock(&m);
        update_state(&state);
        pthread_mutex_unlock(&m);
        compute_more();
    }
}

void *monitor(void *arg) {
    int sig=0;
    for (;;) {
        sigwait(&set, &sig);
        pthread_mutex_lock(&m);
        display(&state);
        pthread_mutex_unlock(&m);
    }
    return 0;
}

```



direct.c



Direct a thread to catch SIGINT

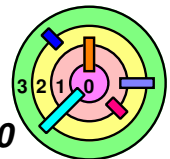
— see "man pthread_sigmask" on Ubuntu 16.04

```
#include "defs.h"
```

```
#define handle_error_en(en, msg) \
    do { errno = en; perror(msg); exit(1); } while (0)
```

```
static void *
sig_thread(void *arg)
{
    sigset_t *set = arg;
    int s, sig;

    for (;;) {
        s = sigwait(set, &sig);
        if (s != 0)
            handle_error_en(s, "sigwait");
        printf("Signal handling thread got signal %d\n",
            sig);
    }
}
```



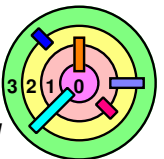
direct.c

```
int
main(int argc, char *argv[])
{
    pthread_t thread;
    sigset_t set;
    int s;

    sigemptyset(&set);
    sigaddset(&set, SIGINT);
    sigaddset(&set, SIGUSR1);
    s = pthread_sigmask(SIG_BLOCK, &set, NULL);
    if (s != 0)
        handle_error_en(s, "pthread_sigmask");

    s = pthread_create(&thread, NULL, &sig_thread,
        (void *) &set);
    if (s != 0)
        handle_error_en(s, "pthread_create");

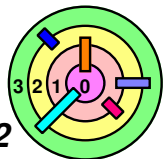
    pause();
}
```



cancel.c

➡ Cancellation

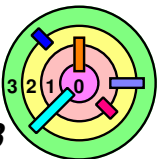
```
#include "defs.h"
#define NUM_THRS 10
pthread_t tid[NUM_THRS];
sigset_t set;
void cleanup(void *arg)
{
    int index=(int)(long)(arg);
    printf("Clean up thread %1d\n", index);
}
void *child(void *arg)
{
    pthread_cleanup_push(cleanup, arg);
    for (;;) {
        usleep(lrand48() % 1000000);
    }
    pthread_cleanup_pop(0);
    return 0;
}
```



cancel.c

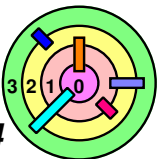
```
void waitall()
{
    int i=0;
    for (i=0; i < NUM_THRS; i++)
        pthread_join(tid[i], 0);
}

void *monitor(void *arg) {
    int i=0, sig=0;
    printf("Press <Ctrl+C>: ");
    fflush(stdout);
    sigwait(&set, &sig);
    printf("\nGot signal %1d\n", sig);
    for (i=0; i < NUM_THRS; i++) {
        while (tid[i] == 0) {
            usleep(100000);
        }
        pthread_cancel(tid[i]);
    }
    return 0;
}
```



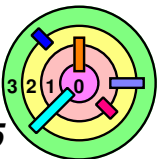
cancel.c

```
int main(int argc, char *argv[])
{
    pthread_t thr;
    int i=0;
    srand48(time(0));
    sigemptyset(&set);
    sigaddset(&set, SIGINT);
    sigprocmask(SIG_BLOCK, &set, 0);
    for (i=0; i < NUM_THRS; i++) {
        pthread_create(&tid[i], 0, child, (void*)(long)i);
    }
    pthread_create(&thr, 0, monitor, 0);
    waitall();
    pthread_join(thr, 0);
    return 0;
}
```



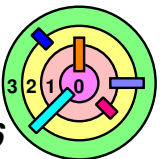
three-threads.c

```
/*
 * Demonstrate that only a thread with SIGINT unblocked
 * will "see" SIGINT.
 * Currently, checking if num == 2 to unblock SIGINT
 * for thread 2. For all other threads, usleep() is
 * never interrupted.
 * Can change the comparison to 1 or 3 to demonstrate
 * how to designate a different thread to only
 * "see" SIGINT.
 */
#include <errno.h>
#include "defs.h"
sigset_t set;
void handler(int signo)
{
    printf("4");
    fflush(stdout);
}
```



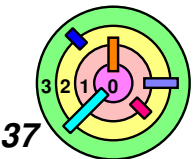
three-threads.c

```
void *child(void *arg) {
    int num=(int) (long) arg;
    if (num == 2) {
        sigprocmask(SIG_UNBLOCK, &set, 0);
    }
    for (;;) {
        printf("%1d", num);
        fflush(stdout);
        if (usleep(500000) != 0) {
            if (errno == EINTR) {
                printf("\nthread %1d interrupted...\n", num);
                fflush(stdout);
            }
        }
    }
    return 0;
}
```



three-threads.c

```
int main(int argc, char *argv[])
{
    int i=0;
    pthread_t t[3];
    sigset(SIGINT, handler);
    sigemptyset(&set);
    sigaddset(&set, SIGINT);
    sigprocmask(SIG_BLOCK, &set, 0);
    for (i=0; i < 3; i++)
        pthread_create(&t[i], 0, child, (void*)(long)(i+1));
    for (;;) {
        printf("0");
        fflush(stdout);
        usleep(500000);
        if (errno == EINTR) {
            printf("\nMain thread interrupted...\n");
            fflush(stdout);
        }
    }
    return 0;
}
```



Kernel Programming Assignments

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