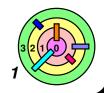
Warmup #2 (Part 1)

Bill Cheng

http://merlot.usc.edu/william/usc/



Multi-threading Exercise

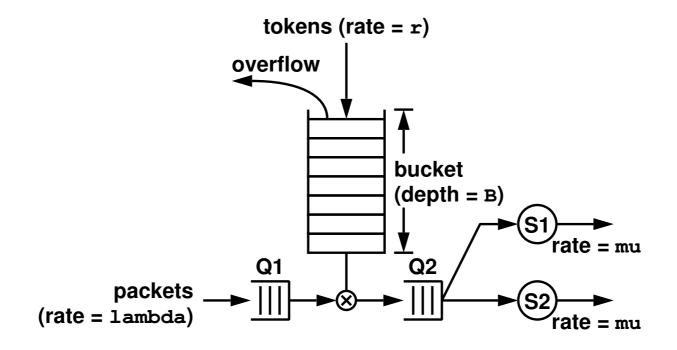


Make sure you are familiar with the *pthreads* library

- Ch 2 of textbook threads, signals
 - additional resource is a book by Nichols, Buttlar, and Farrell "Pthreads Programming", O'Rielly & Associates, 1996
- you must learn how to use pthreads mutex and condition variables correctly
 - pthread_mutex_lock()/pthread_mutex_unlock()
 - pthread_cond_wait()/pthread_cond_broadcast()
 - do not use pthread_cond_signal() for warmup2
- you must learn how to handle UNIX signals (<Ctrl+C>)
 - o sigprocmask()/sigwait()
 - pthread_cancel()
- you may want to learn how to disable/enable cancellation in pthreads
 - pthread_setcancelstate()



Token Bucket Filter





- traffic controller/shaper
- Your job is to implement 4 *cooperating child threads* to move the packets along by following rules described in the spec
 - the main thread creates these threads, join with them, then print statistics

We Are Not Doing Event-driven Simulation



An event queue is a sorted list of events according to timestamps; smallest timestamp at the head of queue

event has zero duration (events can happen at the same time)



Object oriented: every object has a "next event" (what and when it will do next), this event is inserted into the event queue



Execution: remove an event from the head of queue, "execute" the event (notify the corresponding object so it can insert the next event)



Insert into the event queue according to timestamp of a new event; insertion may cause additional events to be deleted or inserted



Potentially repeatable runs (if the same seed is used to initialize random number generator)



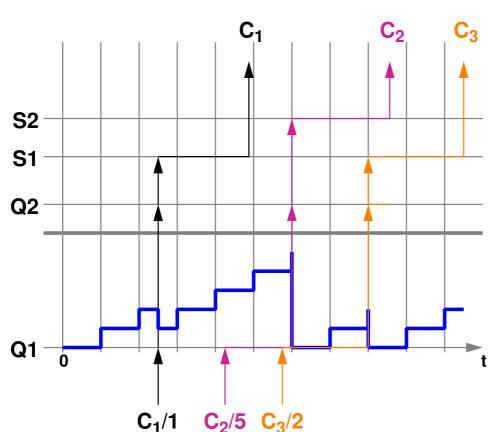
The simulator never "sleeps"; it tries to run as fast as it can to finish the simulation as quickly as possible

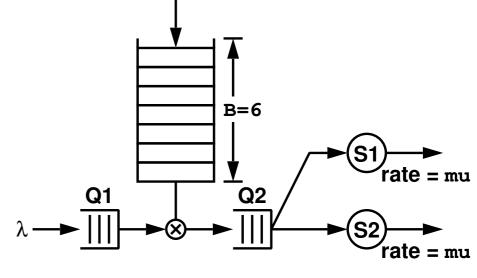
We Are Not Doing Event-driven Simulation



Multiple event can happen at the same time in an *event-driven simulation*

we will not be doing that!





$$- r_3 = d_3 - a_3$$



"Time Driven" Simulation



We will use the words "simulation" and "emulation" interchangeably



No "event queue"

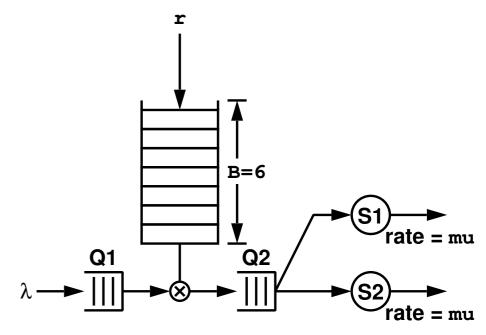
- every active object is implemented as a thread
- threads interacting with one another through the use of shared variables
 - how else can threads "talk" to each other?!



It takes time to execute simulation code

- the time it takes to do all that is part of the simulation
- to simulation the passing of time, call usleep()
 - e.g., if doing something takes x usec, call usleep (x)
 - Ubuntu does not run a "realtime" OS, it's "best effort"
 - usleep(x) will return more than x usec later
 - and sometimes, a lot more than x usec later
 - you need to decide if the extra delay is reasonable or it's due to a bug in your code

"Time Driven" Simulation





Let your machine decide which thread to run next

- results can never be reproducible exactly
- debugging can be more challenging



Compete for resources (such as Q1, Q2, and anything shared), must use a *single mutex*



No busy-waiting

must use a single CV



Arrivals & Departures

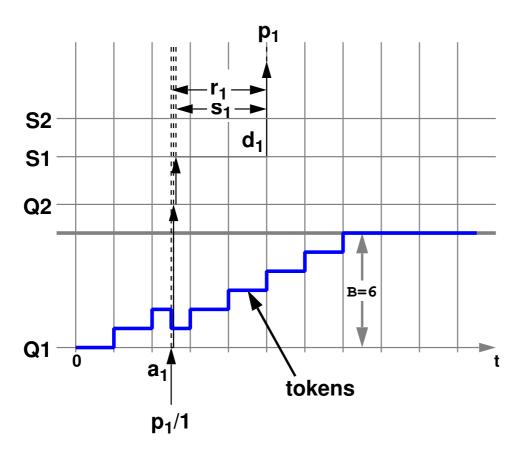
a_i: arrival time

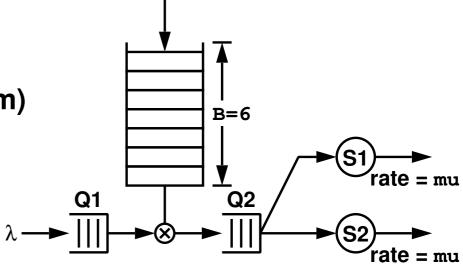
d_i: departure time

- s_i: service time

- r_i: response time (time in system)

 $- q_i^1, q_i^2$: queueing/waiting time





$$- r_1 = d_1 - a_1$$



Arrivals & Departures

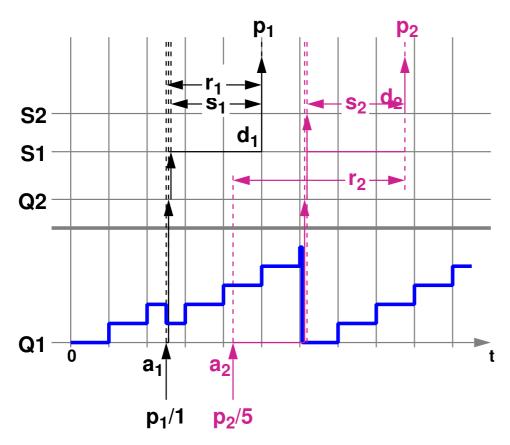
a_i: arrival time

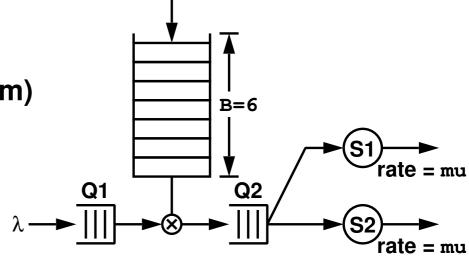
d_i: departure time

- s_i: service time

- r_i: response time (time in system)

 $- q_i^1, q_i^2$: queueing/waiting time





$$- r_2 = d_2 - a_2$$



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Arrivals & Departures

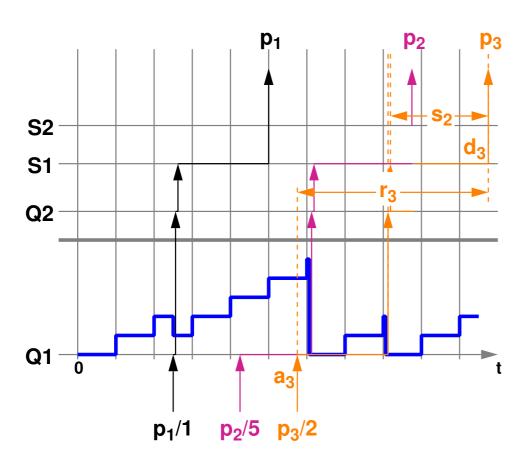
a_i: arrival time

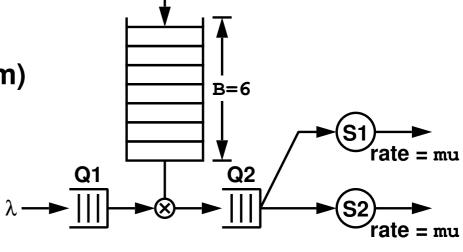
d_i: departure time

s_i : service time

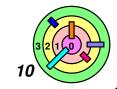
- r_i: response time (time in system)

 $- q_i^1, q_i^2$: queueing/waiting time





$$- r_3 = d_3 - a_3$$



B=6

Q2

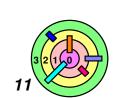
Q1

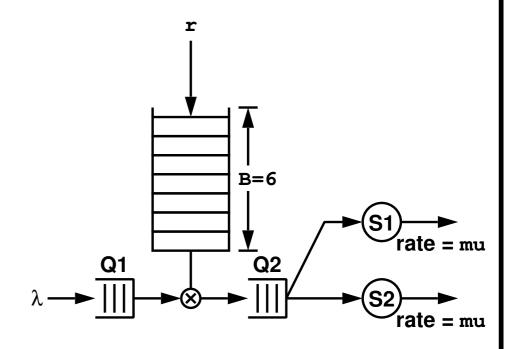
Simulation/Emulation



Two simulation modes

- 1) Deterministic: fixed inter-arrival time $(1/\lambda)$, token requirement (P), and service time (1/mu)
- 2) Trace-driven: every packet has its own inter-arrival time, token requirement, and service time (a line in a "tsfile")
- if you think about it carefully, there is really no difference between these two modes
 - write your code for the trace-driven mode
 - if running in deterministic mode, instead of reading a line from the "tsfile" to create a packet, just create a packet using information stored in global variables

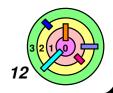






You will need to implement 4 cooperating child threads

- packet arrival thread
- token depositing thread
- two server threads
- these threads work together to simulate the operation of this token bucket filter
 - threads work together using shared variables





Very high level pseudo-code for the packet/token thread:

```
for (;;) {
   sleep
   generate a packet/token
   add packet/token to token bucket filter
}
```

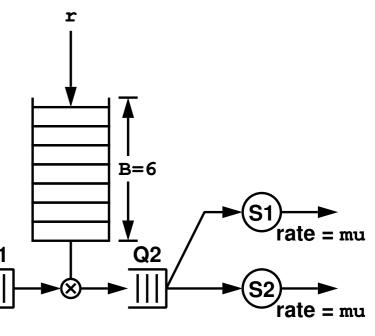
where must you lock and unlock mutex?

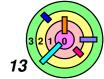


Very high level pseudo-code for the server thread:

```
for (;;) {
  wait for packet in Q2
  remove packet from Q2
  sleep (to transmit packet)
}
```

where must you lock and unlock mutex?



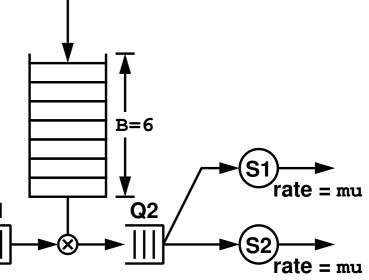


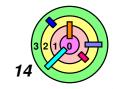


Packet thread pseudo-code (incomplete):

```
for (;;) {
    /* read a line from tsfile if in trace mode */
    get inter_arrival_time, tokens_needed, and service_time;
    /* calculate sleep time from inter_arrival_time */
    usleep(...);
    packet = NewPacket(tokens_needed, service_time, ...);
    pthread_mutex_lock(&mutex);
    Q1.enqueue(packet);
    ... /* other stuff */
    pthread_cond_broadcast(&cv);
    pthread_mutex_unlock(&mutex);
}
```

- must self-terminate as soon as this thread is no longer needed (i.e., no need to generate packets)
- must not call
 pthread_cond_signal()





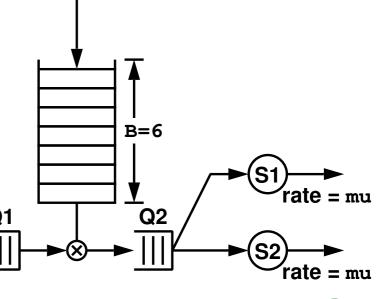


Token thread pseudo-code (incomplete):

```
for (;;) {
    /* calculate sleep time from inter-token arrival time */
    usleep(...);
    pthread_mutex_lock(&mutex);
    tokens++;
    if (first packet in Q1 can now be moved into Q2) {
        packet = Q1.dequeue();
        Q2.enqueue(packet);
        pthread_cond_broadcast(&cv);
        tokens = 0; /* why? */
    }
    pthread_mutex_unlock(&mutex);
}
```

must self-terminate as soon as this thread is no longer needed (i.e., no need to generate tokens)

must not call
pthread_cond_signal()



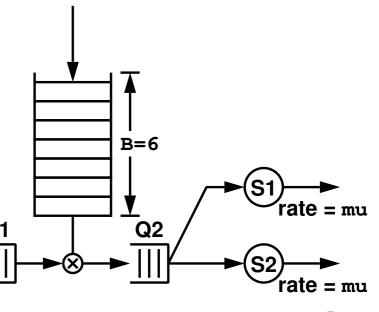


Server threads pseudo-code (incomplete):

same first procedure for both server threads

```
for (;;) {
    /* wait for work */
    pthread_mutex_lock(&mutex);
    while (Q2.length() == 0 && !time_to_quit) {
        pthread_cond_wait(&cv, &mutex);
    }
    packet = Q2.dequeue();
    pthread_mutex_unlock(&mutex);
    /* work */
    usleep(packet.service_time);
}
```

 must self-terminate as soon as this thread is no longer needed (i.e., no need to transmit packets)

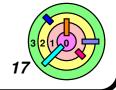






Many other requirements, for example:

- must move a packet at the correct time
 - if a packet is eligible to be moved from Q1 to Q2, it must happen immediately
- all threads must self-terminate when they are no longer needed
- drop packets
 - if the token requirement for an arriving packet is too large (i.e., > B), must drop the packet
- drop tokens
 - if an arriving token finds a full bucket, the token is dropped
- and many more...
 - please read the spec yourself (don't get it from classmates)



Program Printout



Program output must look like what's in the spec

you must NOT wait for emulation to end to print all these

```
Emulation Parameters:
    number to arrive = 20
    lambda = 2
                         (if -t is not specified)
                                                                     from commandline
                          (if -t is not specified)
    mu = 0.35
    r = 4
    B = 10
   P = 3
                          (if -t is not specified)
    tsfile = FILENAME
                              (if -t is specified)
00000000.000ms: emulation begins
00000251.726ms: token t1 arrives, token bucket now has 1 token
00000502.031ms: token t2 arrives, token bucket now has 2 tokens
00000503.112ms: p1 arrives, needs 3 tokens, inter-arrival time = 503.112ms
00000503.376ms: p1 enters Q1
00000751.148ms: token t3 arrives, token bucket now has 3 tokens
00000751.186ms: p1 leaves Q1, time in Q1 = 247.810ms, token bucket now has 0 token
00000752.716ms: p1 enters Q2
00000752.932ms: p1 leaves Q2, time in Q2 = 0.216ms
00000752.982ms: p1 begins service at S1, requesting 2850ms of service
00001004.271ms: p2 arrives, needs 3 tokens, inter-arrival time = 501.159ms
00001004.526ms: p2 enters Q1
00001007.615ms: token t4 arrives, token bucket now has 1 token
00001251.259ms: token t5 arrives, token bucket now has 2 tokens
00001505.986ms: p3 arrives, needs 3 tokens, inter-arrival time = 501.715ms
00001506.713ms: p3 enters Q1
00001507.552ms: token t6 arrives, token bucket now has 3 tokens
00001508.281ms: p2 leaves Q1, time in Q1 = 503.755ms, token bucket now has 0 token
00001508.761ms: p2 enters Q2
00001508.874ms: p2 leaves Q2, time in Q2 = 0.113ms
00001508.895ms: p2 begins service at S2, requesting 1900ms of service
```

Program Printout

```
00003427.557ms: p2 departs from S2, service time = 1918.662ms, time in system = 2423.286ms
00003612.843ms: p1 departs from S1, service time = 2859.861ms, time in system = 3109.731ms
...
?????????ms: p20 departs from S?, service time = ???.??ms, time in system = ???.??ms
?????????ms: emulation ends

Statistics:

average packet inter-arrival time = <real-value>
average packet service time = <real-value>
average number of packets in Q1 = <real-value>
average number of packets in Q2 = <real-value>
average number of packets at S1 = <real-value>
average number of packets at S2 = <real-value>
average time a packet spent in system = <real-value>
standard deviation for time spent in system = <real-value>
token drop probability = <real-value>
packet drop probability = <real-value>
```



Timestamps in the left column must have microsecond resolution

- measured time interval must have microsecond resolution
- use "%.6g" in printf() for <real-value>



A value anywhere in the right column must be the exact differences between two corresponding timestamps



Program Printout

```
...
00003427.557ms: p2 departs from S2, service time = 1918.662ms, time in system = 2423.286ms
00003612.843ms: p1 departs from S1, service time = 2859.861ms, time in system = 3109.731ms
...
?????????ms: p20 departs from S?, service time = ???.??ms, time in system = ???.??ms
?????????ms: emulation ends

Statistics:

average packet inter-arrival time = <real-value>
average packet service time = <real-value>
average number of packets in Q1 = <real-value>
average number of packets in Q2 = <real-value>
average number of packets at S1 = <real-value>
average number of packets at S2 = <real-value>
average time a packet spent in system = <real-value>
standard deviation for time spent in system = <real-value>
token drop probability = <real-value>
packet drop probability = <real-value>
```

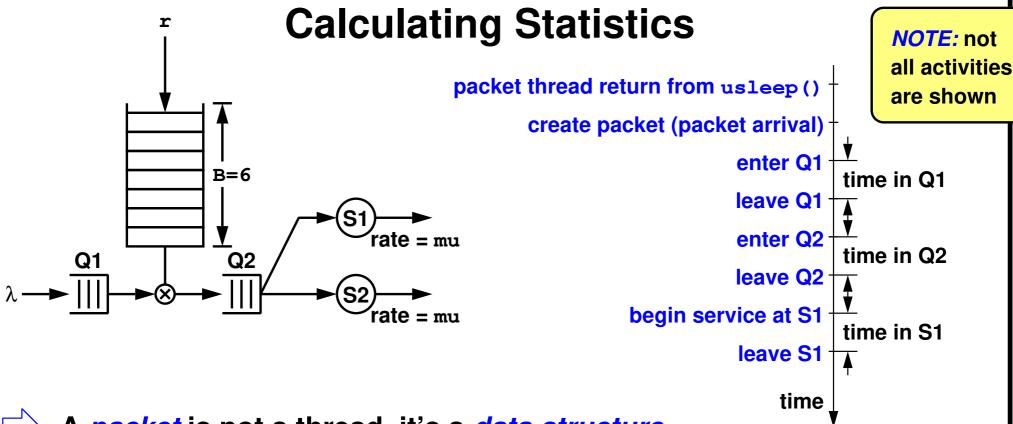


Ex: why must the service time for p1 be exactly 2859.861ms?

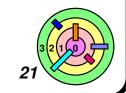
```
3612.843ms - 752.982ms = 2859.861ms
```

- why so strict?
 - your *printout* must be *self-consistent*





- A packet is not a thread, it's a data structure
 - it should have 7 timestamps to store "measured" information
 - it should also store "packet specification" (such as specified inter-arrival time, token requirement, service time)
 - these are not "measured" values
- Some packets needs to be excluded from certain statistics
 - add to corresponding statistics only when a packet is being ejected



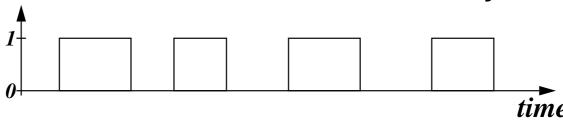
Mean and Standard Deviation



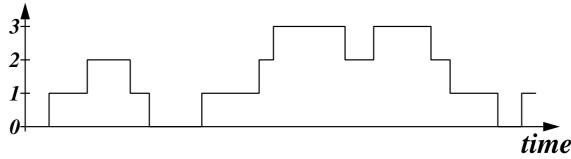
- for *n* samples, add up all the time and divide by *n*



same a fraction of time the server is busy



Average number of packets at Q1





$$Var[X] = E[X^2] - (E[X])^2$$

must use the population variance equation

